A Comprehensible Guide To J1939

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SAE J1939 has become the accepted industry standard and the vehicle network technology of choice for off-highway machines. This resource provides profound information on the J1939 message format and network management.

A Comprehensible Guide to Controller Area Network by Wilfred Voss represents the most thoroughly researched and most complete work on CAN available in the marketplace. It includes:A Brief History of CAN, Main Characteristics, Message Frame Architecture, Message Broadcasting, Bus Arbitration, Error Detection & Fault Confinement, CAN Physical Layer, and more?

The Importance of servo motor sizing should not be underestimated. Proper motor sizing will not only result in significant cost savings by saving energy, reducing purchasing and operating costs, reducing downtime, etc.; it also helps the engineer to design better motion control systems. However, the knowledge of mechanical systems and their influence on motor speed, inertia and torque requirements seems to decline in a world where modern technology aspects, such as tuning and programming, seem to be the main focus. The motor sizing process involves a number of mathematical equations, which are most certainly documented, but not necessarily with the motor sizing process in mind. This book focuses primarily on servo motor sizing and it documents in detail the inertia and torque calculations of standard mechanical components and the motor selection process.

This book, written by a leading expert in the field of Controller Area Network (CAN) technologies, represents the perfect guide to implementing an SAE J1939 protocol stack for embedded systems. The book is filled with numerous C/C++ code examples and valuable documentation of the resulting J1939 vehicle network data traffic. It explains in great detail the inner workings of the protocol through designing and transmitting J1939 data frames, receiving and processing J1939 data frames, and simulating J1939 ECUs (Electronic Control Units). Other Arduino sketches (software projects) include a J1939 network scanner, and a simple SAE J1939 to USB Gateway application with associated Windows GUI (Visual Studio C# project). The collection of sketches is concluded by the ARD1939 project, a fully functional SAE J1939 protocol stack for the Arduino Uno and Mega 2560. As an added value, the included proof of concept explains (by means of code examples and bus traffic recordings) the details of the Transport Protocol (TP) according to SAE J1939/21 (BAM Session, RTS/CTS Session) and the Address Claim Procedure according to SAE J1939/81. In combination with the low-cost and high-level user-friendliness approach of the Arduino environment, this book represents the ideal platform to learning and implementing embedded applications with the SAE J1939 protocol stack.

This book to offers a hands-on guide to designing, analyzing and debugging a communication infrastructure based on the Controller Area Network (CAN) bus. Although the CAN bus standard is well established and currently used in most automotive systems, as well as avionics, medical systems and other devices, its features are not fully understood by most developers, who tend to misuse the network. This results in lost opportunities for better efficiency and performance. These authors offer a comprehensive range of architectural solutions and domains of analysis. It also provides formal models and analytical results, with thorough discussion of their applicability, so that it serves as an invaluable reference for researchers and students, as well as practicing engineers.

While the Arduino is not widely considered an industrial-strength solution, it provides, due to its low price and ease of programming, the perfect prototyping platform for all kinds of Controller Area Network (CAN) applications. This book, written by a leading expert on CAN technologies, guides the reader through the process of acquiring all necessary hardware and software components, the implementation of the CAN driver, and the implementation of

programs (Arduino Sketches) to read, send, process, and display data from and to a CAN network. The collection of programming examples cumulates into a full-fledged USB-to-CAN Gateway communicating with a Windows/Linux PC. This book will enable you to achieve CAN functionality literally within only a few hours.

This book addresses the various challenges and open questions relating to CAN communication networks. Opening with a short introduction into the fundamentals of CAN, the book then examines the problems and solutions for the physical layout of networks, including EMC issues and topology layout. Additionally, a discussion of quality issues with a particular focus on test techniques is presented. Each chapter features a collection of illuminating insights and detailed technical information supplied by a selection of internationally-regarded experts from industry and academia. Features: presents thorough coverage of architectures, implementations and application of CAN transceiver, data link layer and so-called higher layer software; explains CAN EMC characteristics and countermeasures, as well as how to design CAN networks; demonstrates how to practically apply and test CAN systems; includes examples of real networks from diverse applications in automotive engineering, avionics, and home heating technology.

Modern cars are more computerized than ever. Infotainment and navigation systems, Wi-Fi, automatic software updates, and other innovations aim to make driving more convenient. But vehicle technologies haven't kept pace with today's more hostile security environment, leaving millions vulnerable to attack. The Car Hacker's Handbook will give you a deeper understanding of the computer systems and embedded software in modern vehicles. It begins by examining vulnerabilities and providing detailed explanations of communications over the CAN bus and between devices and systems. Then, once you have an understanding of a vehicle's communication network, you'll learn how to intercept data and perform specific hacks to track vehicles, unlock doors, glitch engines, flood communication, and more. With a focus on low-cost, open source hacking tools such as Metasploit, Wireshark, Kayak, can-utils, and ChipWhisperer, The Car Hacker's Handbook will show you how to: –Build an accurate threat model for your vehicle –Reverse engineer the CAN bus to fake engine signals –Exploit vulnerabilities in diagnostic and data-logging systems –Hack the ECU and other firmware and embedded systems –Feed exploits through infotainment and vehicle-to-vehicle communication systems –Override factory settings with performance-tuning techniques –Build physical and virtual test benches to try out exploits safely If you're curious about automotive security and have the urge to hack a two-ton computer, make The Car Hacker's Handbook your first stop.

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