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ISO - ISO 8373:2012 - Robots and robotic devices □ Vocabulary

ISO 8373 was prepared by Technical Committee ISO/TC 184, Automation systems and integration, Subcommittee SC 2, Robots and robotic devices. This second edition cancels and replaces the first edition (ISO 8373:1994), which has been technically revised and expanded to include both industrial robots and service robots.

ISO 8373:2012(en), Robots and robotic devices ? Vocabulary

ISO 8373 Manipulating industrial robots □ Vocabulary It is the ISO standard that defines terms relevant to manipulating industrial robots operated in a manufacturing environment.

ISO 8373 - Wikipedia

ISO 8373:2012 defines terms used in relation with robots and robotic devices operating in both industrial and non-industrial environments.

ISO 8373 - European Standards Online Store

This International Standard specifies vocabulary used in relation with robots and robotic devices

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operating in both industrial and non-industrial environments. The document is the revision of ISO 8373:1994 by developing new terminologies for service robots. With existing 96 terms, 6 terms are removed and 67 terms are introduced.

ISO 8373:2012

Robots and robotic devices - Vocabulary (ISO 8373:2012, IDT)

Robots and robotic devices - Vocabulary (ISO 8373:2012, IDT)

BS ISO 8373:2012: Title: Robots and robotic devices. Vocabulary: Status: Under review, Current: Publication Date: 30 September 2012: Normative References(Required to achieve compliance to this standard) No other standards are normatively referenced: Informative References(Provided for Information) ISO 9409-1, ISO 10218-1, ISO 9787, ISO 9283, ISO 9000:2005, ISO 10218-2, ISO 11593, ISO/TR 13309 ...

BS ISO 8373:2012 - Robots and robotic devices. Vocabulary

BS ISO 8373:2012: Title: Robots and robotic devices. Vocabulary: Status: Work in hand, Current: Publication Date: 30 September 2012: Normative References(Required to achieve compliance to this standard) No other standards are normatively referenced: Informative References(Provided for Information) ISO 9409-1, ISO 10218-1, ISO 9787, ISO 9283, ISO 9000:2005, ISO 10218-2, ISO 11593, ISO/TR 13309 ...

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ISO/TR 8373:1988 Manipulating industrial robots – Vocabulary. General information Status : Withdrawn. Publication date : 1988-09. Edition : 1 Number of pages : 15 Technical Committee: ISO/TC 184. Automation systems and integration. ICS : 01.040.25 Manufacturing engineering (Vocabularies) 25.040.30 Industrial robots. Manipulators. Life cycle. A standard is reviewed every 5 years 00 ...

ISO - ISO/TR 8373:1988 - Manipulating industrial robots ...

1.2.1 Definition (ISO 8373:2012) and delimitation The annual surveys carried out by IFR focus on the collection of yearly statistics on the production, imports, exports and domestic installations/shipments of industrial robots (at least three or more axes) as described in the ISO definition given below.

1.2 Industrial robots - definition and classification

ISO 8373 March 1, 2012 Robots and robotic devices – Vocabulary This International Standard defines terms used in relation with robots and robotic devices operating in both industrial and non-industrial environments.

ISO 8373 - Robots and robotic devices – Vocabulary ...

ISO 8373 Manipulating industrial robots – Vocabulary An industrial robot is a robot system used for manufacturing. Industrial robots are automated, programmable and capable of movement on three or more axis. A vocabulary is a set of familiar words within a person's language.

ISO 8373 - WikiMili, The Free Encyclopedia

More information about ISO/TC 299 –Robotics– including a list of published standards as well as a list

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of standards under development can be found at the ISO webpage. Robot definitions at ISO. IFR members use the definitions contained in the international standard ISO 8373 "Vocabulary" when compiling statistics of industrial robots in particular countries for example. Accordingly, an ...

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ISO 8373:1994 This document has been replaced. View the most recent version. Manipulating industrial robots - Vocabulary. standard by International Organization for Standardization, 12/01/1994. Languages: English Amendments, rulings, and supplements: ISO 8373/AMD1:1996. Corrigenda: ISO 8373/COR1:1996

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International Transaction Journal of Engineering, Management, & Applied Sciences & Technologies publishes a wide spectrum of research and technical articles as well as reviews, experiments, experiences, modelings, simulations, designs, and innovations from engineering, sciences, life sciences, and related disciplines as well as interdisciplinary/cross-disciplinary/multidisciplinary subjects. Original work is required. Article submitted must not be under consideration of other publishers for publications.

This Standard specifies the terms and definitions, requirements and test methods for assisted surgical medical equipment and assisted surgical medical system employing robotic technology.

This book presents the latest research advances in the theory, design, control, and application of robot systems intended for a variety of purposes such as manipulation, manufacturing, automation, surgery, locomotion, and biomechanics. Several chapters deal with fundamental kinematics in nature, including synthesis, calibration, redundancy, force control, dexterity, inverse and forward kinematics, kinematic

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singularities, and over-constrained systems. This book is a compilation of the extended versions of the very best papers selected from the many that were presented at the Asian Conference on Computer-Aided Surgery held September 16–18, 2013, in Tokyo, Japan (ACCAS 2013).

Like the Internet before it, robotics is a socially and economically transformative technology. Robot Law explores how the increasing sophistication of robots and their widespread deployment into hospitals, public spaces, and battlefields requires rethinking of a wide variety of philosophical and public policy issues, including how this technology interacts with existing legal regimes, and thus may inspire changes in policy and in law. This volume collects the efforts of a diverse group of scholars who each, in their own way, has worked to overcome barriers in order to facilitate necessary and timely discussions of a technology in its infancy. Identifying controversial legal, ethical, and philosophical problems, the authors reveal how issues surrounding robotics and regulation are more complicated than engineers could have anticipated, and just how much definitional and applied work remains to be done. This groundbreaking examination of a brand-new reality will be of interest and of use to a variety of groups as the authors include engineers, ethicists, lawyers, roboticists, philosophers, and serving military.

Provides a thorough discussion of robots and robotics technology.

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